# Resilient & Intelligent NextG Systems (RINGS)

Principal Investigator (PI) Project Summary Moe Z. Win

> Massachusetts Institute of Technology

DEFENSE 🕲 NIST 🗯 🏂 Google III intel.



Microsoft NOKIA

Qualcomm

Qualcomm Technologies, Inc **vm**ware



**National Science Foundation** 





# Resilient and Low-Latency Networks for Situation Awareness in the Factory of the Future

Moe Z. Win and Dimitri P. Bertsekas Laboratory for Information and Decision Systems Massachusetts Institute of Technology

> Victor B. Lawrence Intelligent Networked Systems Center Stevens Institute of Technology

#### MOTIVATION

### Motivation: Factory of the Future (RV:B4)

- Factory of the future (FoF) is inherently a multi-agent system composed of heterogeneous nodes: machines, workers, workpieces etc.
- Coordination (communication and control) among heterogeneous nodes facilitates operational resiliency: adaptability, autonomy, and reliability
- Dense and dynamically-changing factory environments create harsh conditions for communication and control of networked systems



https://www.bcg.com/publications/2016/leaning-manufacturing-operations-factory-of-future

### Latency in FoF

- Two types of latency in the network
  - communication latency: delay in successful transmission of data packets due to
    - queueing of data packets in the network
    - resource coordination at edge nodes
  - computation latency: delay caused by the processing of data packets due to
    - multimodal data fusion in inference
    - control action generation in decision making
- The latency-accuracy trade-off drives decisions made at the network
  - low latency but low accuracy at the edge cloud
  - high latency but high accuracy at the core cloud

# Gaps and Objectives

- Gaps
  - existing works on localization do not account for sensing latency and may lead to poor performance when data packets are not readily available
  - a systematic design of localization and decision making accounting for the latency in sensing, communication, and computation is still lacking
- Objective: develop latency-resilient algorithms for network inference and control to facilitate situational awareness and decision making in FoF

# HIGH-LEVEL PROJECT VIEW: PLAN AND APPROACH

# **FoF: Inference and Control Loop**

- FoF has the following constituents
  - physical layer: FoF agents
  - sensing layer: multimodal sensors
  - inference layer: processor nodes for localization and navigation
  - control layer: processor nodes for action generations



### Project Plan

- Our contributions to NextG resiliency, network intelligence, performance, and security are as follows
  - operational resilience under latency
  - high-accuracy localization and near-optimal control action generation
  - intelligent network resource coordination
- Establish two lines of research to unleash technologies that are essential for resilient networks in the FoF
  - adaptive low-latency network localization
  - latency-resilient decision making

# ADAPTIVE LOW-LATENCY NETWORK LOCALIZATION

# **Goals and Challenges**

- Localization and tracking is important for FoF
- Multiple sensor nodes observe the system state and communicate within themselves or with processor nodes over a network to accurately infer the state of the system

#### • Goals

- design efficient algorithms for high-accuracy localization by fusing sensed data obtained from heterogeneous devices in FoF
- develop a framework for inference in the presence of network latency

#### • Challenges

- heterogeneity of sensors used in FoF
- communication and computing latency in the network
- uncertainty in temporal association of sensed data with measurement time

- Soft information
  - extraction methods for soft feature information and soft context information
  - fusion of soft information from heterogeneous observations using statistical inference theory



#### • Belief propagation

- iterative evaluation of an approximate posterior distribution for the target positions
- tractable association of sensing data with the time instants at which they are measured



### LATENCY-RESILIENT DECISION MAKING

# **Goals and Challenges**

- Resilient decision making and the ability to adapt and coordinate agent resources is crucial for NextG networks
- FoF requires the network to efficiently use its limited energy, communication, and sensing resources for inferring and controlling the states of FoF agents
- Goals
  - design system-wide control policies for partially observable target nodes in the factory
  - develop efficient coordination strategies for sensing and communication
- Challenges
  - performance of the decision layer is limited by the inference layer
  - partial observability of target states is complicated by network-wide latency
  - multi-agent decision problems are difficult to solve

- Partially observable Markov decision processes (POMDPs)
  - model the decision problem as a POMDP
  - compute the belief state using proposed latency-resilient localization algorithms
  - employ dynamic programming for obtaining near-optimal policies for the POMDP



#### Rollout

- rollout approach for approximate dynamic programming has two basic constituents:
  - multi-step lookahead optimization
  - a base (heuristic) policy for approximation of reward-to-go
- approximate the reward-to-go at the end of the lookahead horizon using a heuristic policy
- obtain a sequence of controls for the lookahead horizon using nonlinear programming or optimal control techniques



### STRATEGIC PROJECT SUMMARY

# **Strategic Project Summary**

- Expected research outputs
  - algorithms for latency-aware localization and tracking
  - algorithms for latency-resilient decision making
  - dissemination of research results: journal papers, conference presentations, and tutorials

#### • Helpful resources

- specialized knowledge related to FoF
- sensing and communication data obtained in factories
- Collaboration and synergies
  - standardization bodies for 5G and B5G
  - industrial partners